



PREFERRED  
RELIABILITY  
PRACTICES

GUIDELINE NO. GT-TE-2402  
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# NEAR FIELD MEASUREMENT FOR LARGE APERTURE ANTENNA PATTERN DETERMINATION

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## **Guideline:**

Use near field antenna measurement facilities for determination of far field antenna patterns of large aperture, high frequency antennas<sup>1</sup>. This guideline supports reliable communications with spacecraft.

## **Benefits:**

For high frequency, large aperture antennas, near field antenna facilities provide more timely, cost effective, and efficient pattern measurements resulting in the following benefits:

1. protection for environmentally (and gravitationally) sensitive antennas from elements such as wind, rain, smog, wildlife, etc.;
2. characterization of complete far field pattern over region corresponding to sampled near field;
3. measurements are not affected by weather or uncontrolled reflections;
4. diagnostic capability for feed misalignment, phased array element amplitude and phase excitation, holographic determination of reflector surface accuracy; and
5. depending on range geometry, accurate characterization of far sidelobes and backlobe patterns;
6. accurate far-field pattern construction of both co- and cross-polarization patterns from the same set of near field data.

## **Center to Contact for More Information:**

Lewis Research Center (LeRC), Jet Propulsion Laboratory (JPL), Johnson Space Center (JSC)

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<sup>1</sup> For the purposes of this Guideline, "large aperture, high frequency antennas" are those antennas for which the far field ( $D^2/\lambda$ ) distance exceeds reasonable building size and/or controlled range space. See Technical Rationale in this Guideline.



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scan plane using a Hewlett Packard 8510 automated network analyzer; and Hewlett Packard 8340 frequency synthesizers are used to provide RF and local oscillator signal sources. Fiber optic links are used to distribute local oscillator signal to RHG mixers. The data acquisition and system control are performed by an on-site computer. Data processing is performed in an offsite computer facility. The LeRC near field test facility was designed for frequencies of operation from 0.8 GHz to 60 GHz. The scanner can test antennas having a  $D/\lambda$  to 1100 for antenna apertures up to 18 ft.  $D$  is a characteristic dimension of the test antenna (i.e. diameter for a circular aperture antenna), and  $\lambda$  is the wavelength for the antenna operating frequency. For detailed description of design, operation and performance see references 1, 2, and 3. Other near field antenna test facilities within NASA (see Appendix) are located at JPL, and JSC.

In selecting a near field range for antenna testing, just as in selecting a far field range, attention must be given to the determination of measurement uncertainty. This can be of importance for applications requiring low measurement uncertainties or high precision. As in far field ranges, near field ranges are affected by electronic equipment sources of error such as drift, noise, dynamic range, nonlinearity, signal leakage, and reflections. However, the error manifestations may differ between the near field and far field ranges. In addition, the near field range is affected by error sources from probe interactions with the near fields, probe position, antenna alignment, and errors caused by flexing cables. Mathematical errors are generally very small in comparison to experimental errors. For more information on the effects of errors in near field antenna testing see references 6 and 7.

### **Technical Rationale:**

The measurement of far field antenna patterns can be accomplished by using a far field range or a near field measurement facility. For measurements made in the far field, the distance between the test antenna and the measurement transmitting source (or receiver) must be greater than  $2D^2/\lambda$ , where  $D$  is a characteristic dimension of the test antenna and  $\lambda$  is the wavelength. (For antennas having significant aperture phase deviations and requiring low measurement uncertainties, the spacing required can exceed  $8D^2/\lambda$ .) From this relation it can be seen that large distances are required for far field testing of large aperture, high frequency antennas. For example the test distance required for far field pattern measurement of a 12 GHz parabolic reflector antenna with a 12 ft diameter would be 3500 ft. Because of the large distances the far field tests are conducted outdoors where the testing is constrained by weather and the transmission path is influenced by the weather. In addition, the path between the test antenna and the source must be controlled to preclude variations due to reflections from traffic entering the path.

The determination of far field antenna patterns, obtained by using near field measurements, has been demonstrated and proven, references 4 and 5. The validity and accuracies have been shown to be comparable to measurements made using far field ranges, under conditions controlled to preclude environment errors. The determination of far field antenna patterns, from near field measurements, can be done indoors in a protected, controlled environment, where the testing is

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not constrained by the effects of weather on the test antenna or results. The anechoic environment can provide protection for costly flight hardware from weather, smog, wildlife, and other environmental hazards. The region of testing can be designed and controlled to minimize the effects of reflections. And, for spacecraft antennas designed in a microgravity environment, the effects of gravitational deformations can be reduced or eliminated when tests are conducted with vertical boresite orientations. These advantages are gained at the expense of increased measurement times and complexity. Many measurements must be made to define the near field pattern, see reference 7. The set of near field measurements must be made up of complex field quantities (e.g.,  $a+jb$ ) and an accurate determination of probe position. Data acquisition time is a function of desired accuracy, aperture area, and frequency. In addition, computation time is required to transform the near field data to the far field patterns.

### **Impact of Nonpractice:**

Failure to use near field measurements for determining far field patterns of high frequency, large aperture antennas, constrains testing due to exposure of test antenna to weather. In addition, test results can may be influenced by local weather conditions and the existence of uncontrolled reflections from traffic within the region of the test path.

### **Appendix:**

This appendix provides a listing of near field antenna test facilities within NASA, and lists their salient characteristics. The table below lists the location of the facility, the type of scanning surface used, the size of the scanning plane, the maximum frequency of operation, and antenna boresite orientation. The table also describes the mode of operation supported for the test antenna, i.e. transmitting and/or receiving, and notes if the test antenna must be moved during testing.

Location	Type	Size, m	Frequency, GHz	Boresite Orientation	Mode	Probe motion	Note
JPL	Cylindrical	5.2	18	horizontal	trans	1d	rotate antenna
JPL	Plane polar	6.1	32	vertical	trans	1d	rotate antenna
JSC	Plane rectangular	12.2x12.2	40	vertical	trans	2d	fixed
LeRC	Plane rectangular	6.7x6.7	60	horizontal	trans rec	2d	fixed

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The following is a brief description of each center's near-field capability.

### **Jet Propulsion Laboratory**

#### Cylindrical Near-Field Facility

The cylindrical near-field scanning facility at JPL contains an anechoic chamber that is 20x20x40. The chamber contains two automated positioners, one for the test antenna and the other for the sampling probe. Cylindrical near-field scanning is performed by rotating the test antenna in an azimuth direction while the probe step along the z-direction after the test antenna completes a full 360 degree rotation. The Jet Propulsion Laboratory has conducted recently an extensive research in the area of cylindrical near-field that led to the development of efficient and fast algorithms for far field construction, probe pattern compensation, probe characterization, and an error analysis.

#### Plane-polar Near-Field Facility

The plane-polar near-field range facility is located in an anechoic chamber with a dimension of 20'x20'x40'. The facility utilizes two automated positioners, one for the test antenna (generally has a large planer aperture) and the other for the sampling probe. The test antenna aperture is horizontally situated close to the ground with the aperture placed in the x-y plane facing up and rotated azimuthally around the z-axis. The probe is situated close to the ceiling facing down with a single linear translational motion in the x or y direction above and across the center of the test antenna. The probe is generally separated several wavelengths away from the test antenna. The near-field amplitude and phase data are taken with the probe initiated at a particular incremental location while the test antenna is rotated 360 o incrementally, which is repeated at the next incremental probe location, etc. The probe has a total rms deflection of 0.025 cm over the total run of the carriage (7m long). This provides sufficient accuracy for measurement up to Ku-band and can be improved for Ka-band measurement.

### **Johnson Space Center**

#### Plane Rectangular Near-Field Facility

The anechoic chamber at the Johnson Space Center is capable of testing antennas up to 30 ft in diameter. The frequency range of the facility is from 1.0 Ghz to 60.0 Ghz. The near-field facility includes a two-axis horizontal scanning system. The scanner is configured with a RF probe which can function as a transmitter or receiver. The probe travels in the Y-direction for each step increment moved by the translation beam in the X-direction. The movement of the scanner will describe a raster scan geometry.

During testing, the position of the test antenna will be fixed such that its boresight will be perpendicular to the horizontal scan plane of approximately 40'x38'. The planarity of the scanner as described by the probe tip motion will be flat within +/- 0.005 inch. This accuracy is especially critical at the maximum operating frequency of 60.0 GHz.

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## References:

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